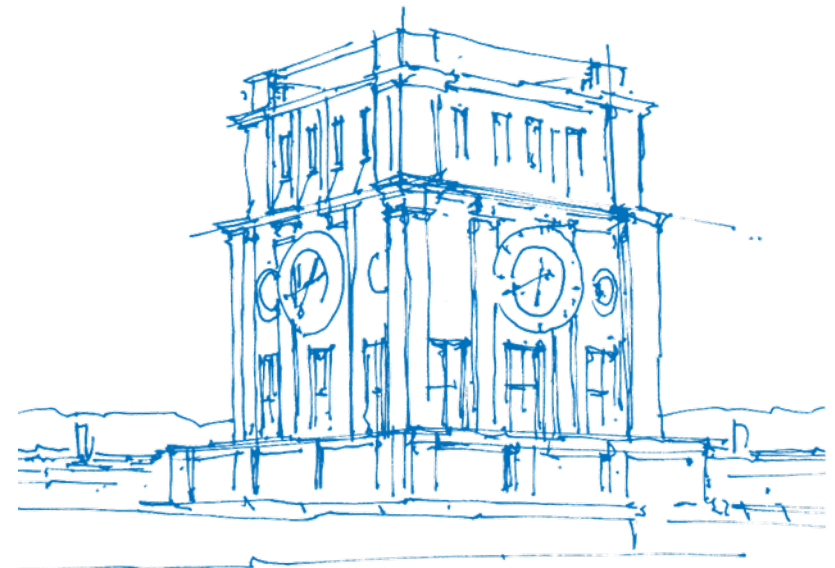


QoS Provisioning in Industrial Wireless Sensor Networks

Samuele Zoppi, H. Murat Gürsu, Wolfgang Kellerer

Chair of Communication Networks
Technical University of Munich, Germany

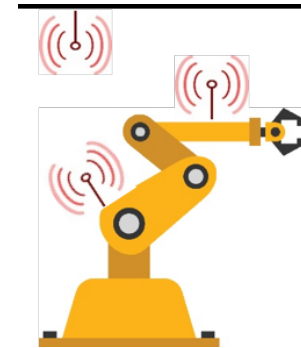


TUM Uhrenturm

Munich, 1st December 2017

Background

Next-generation industrial automation systems will be **wirelessly** interconnected [HPO16].

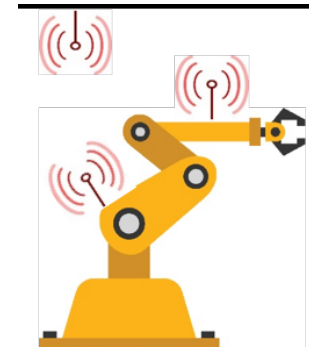


Industrial NCS.

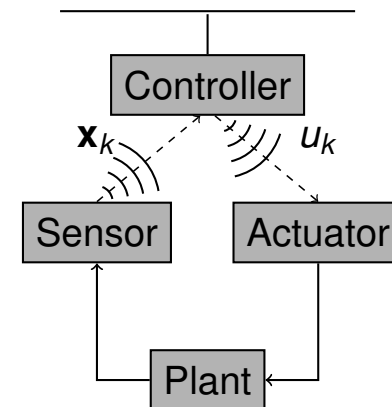
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Networked Control Systems (NCS): control loops *closed* over the network.



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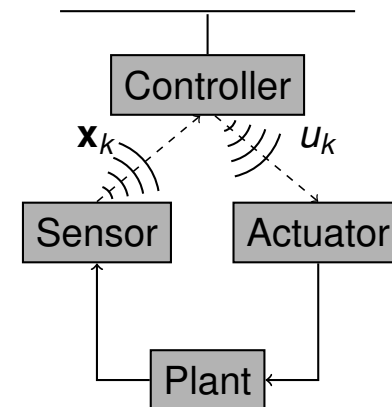
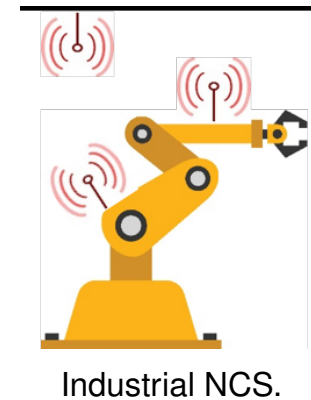
Networked Control Systems (NCS): control loops *closed* over the network.

Stochastic LTI control system:

$$\mathbf{x}_{k+1} = \mathbf{A}\mathbf{x}_k + \mathbf{B}u_k + \mathbf{w}_k,$$

$$u_k = -\mathbf{K}\mathbf{x}_k,$$

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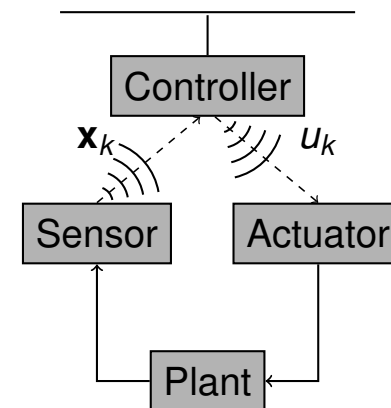
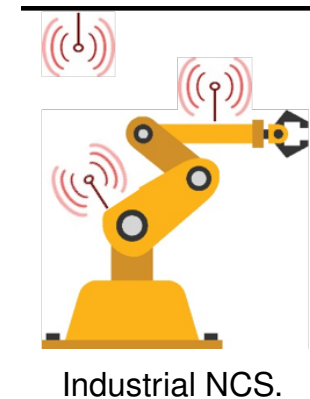
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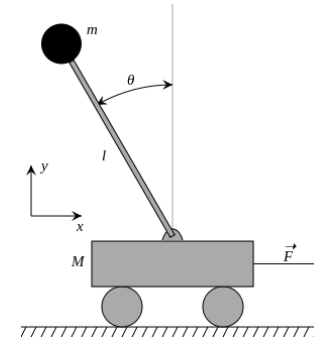
Sensor sends \mathbf{x}_k to the Controller.

Controller computes and sends u_k to the Actuator.

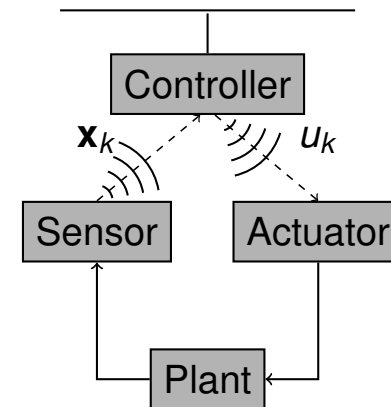


Background (2)

Inverted pendulum as benchmark NCS **application**.



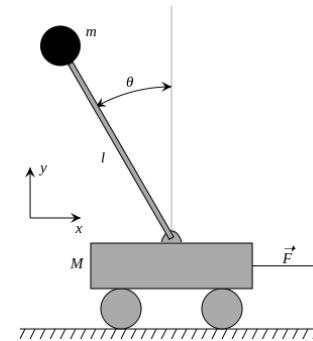
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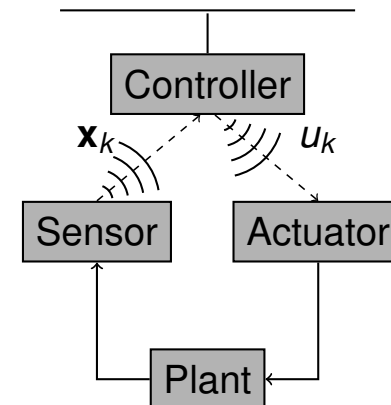
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Sampling frequency: 20 Hz.



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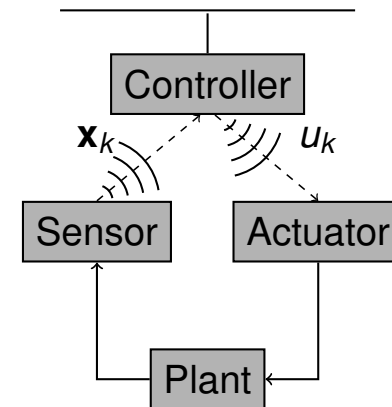
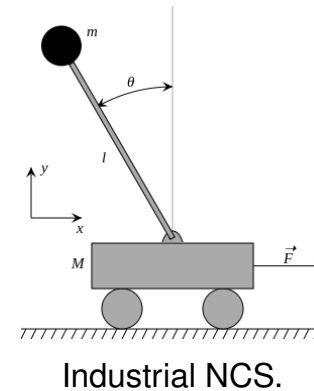
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Uplink traffic:

$$\mathbf{x}_k = \begin{bmatrix} x_k \\ \dot{x}_k \\ \theta_k \\ \dot{\theta}_k \end{bmatrix} \rightarrow 256 \text{ bits @ } 20\text{Hz} = 5 \text{ kbps.}$$



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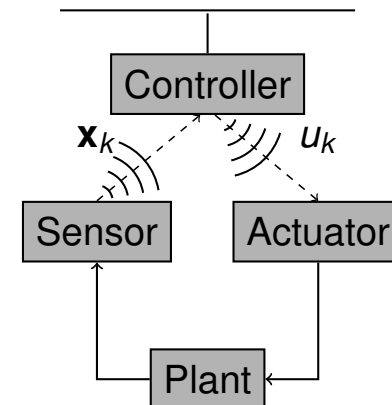
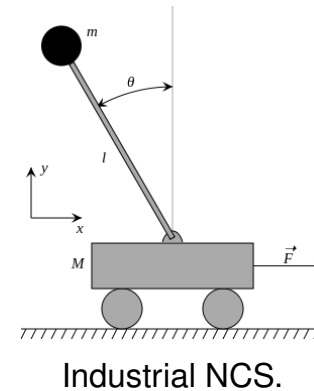
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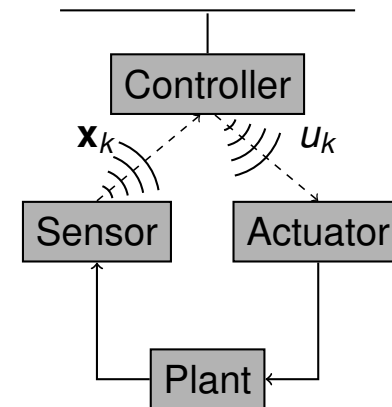
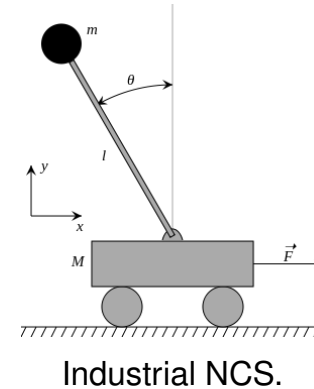
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WSN (PHY IEEE 802.15.4) link \rightarrow 250 kbps.



Motivation

Wireless Sensor Networks (WSN) can support NCS traffic.

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Control loops pose strict **QoS requirements** on wireless communications.

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Approach:

1. Definition of a QoS provisioning framework for IWSN.
2. Implementation of the framework in a testbed.

Outline

Background & Motivation

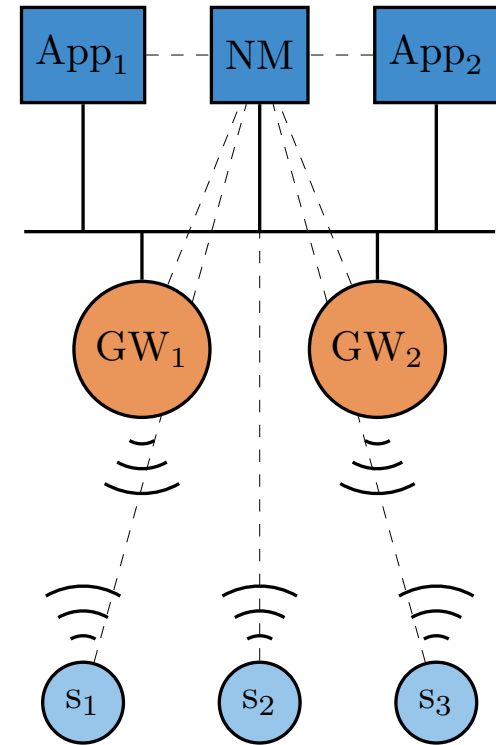
QoS Provisioning Framework

Implementation

Conclusions & Further Work

Network Architecture

Centralized, star topology.



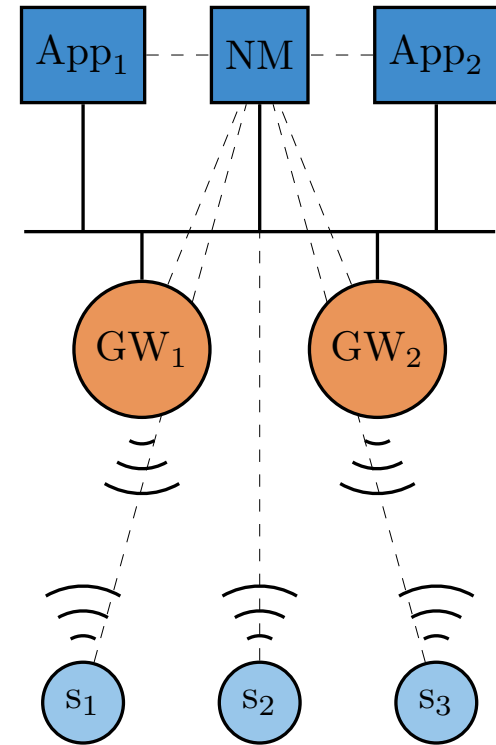
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Network elements:

1. **Application (App)**: industrial NCS application
2. **Network Manager (NM)**: manager of the Network Resources of the entire WSN
3. **Gateway (GW)**: interface btw the WSN devices, the NM and Apps
4. **Sensor (s)**: WSN device



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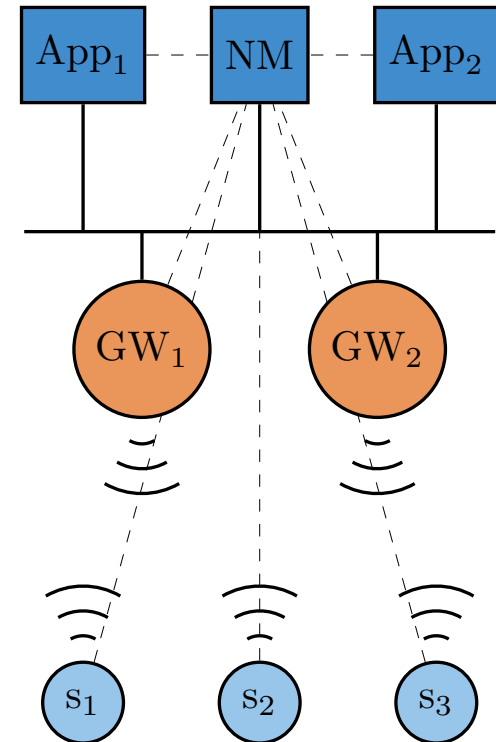
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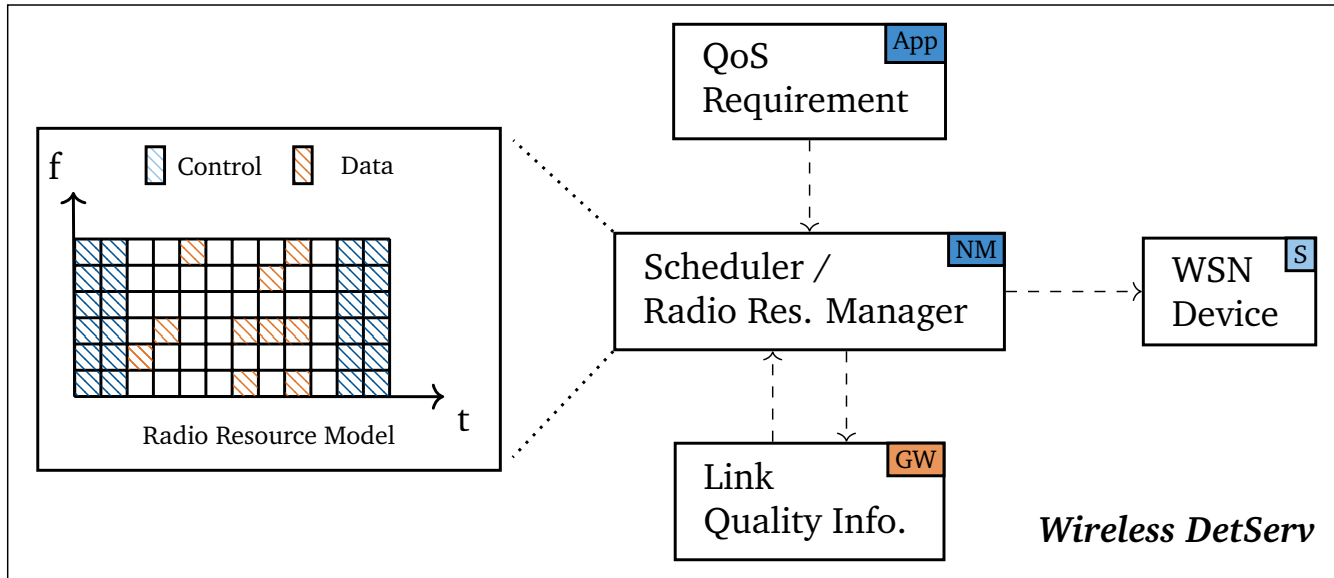
Data links btw NM and WSN devices through the GW.

Control links btw App and WSN devices through the GW.

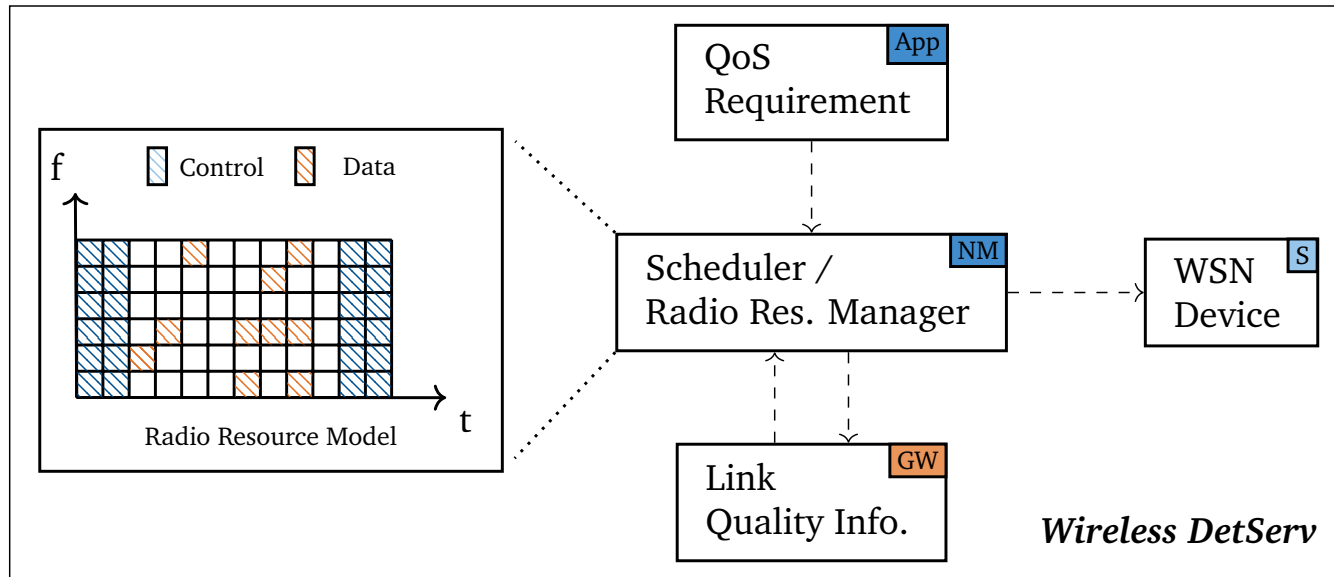


Network architecture.

QoS Framework (1)



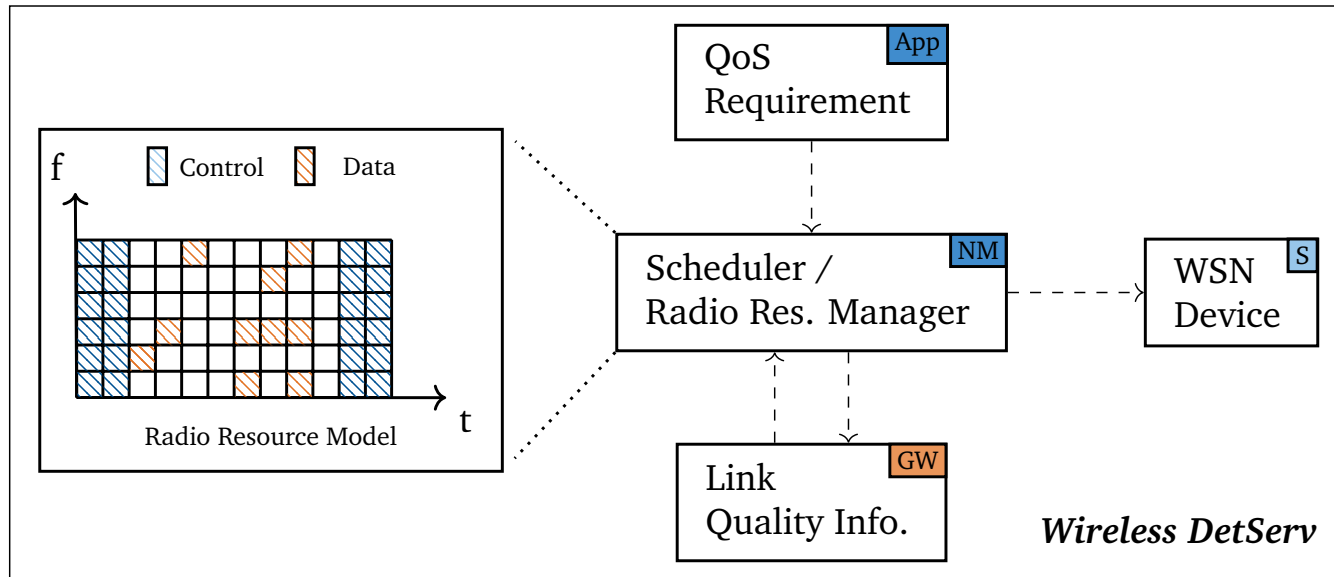
QoS Framework (1)



Radio Resource Manager **inputs**:

1. QoS requirements from the application.
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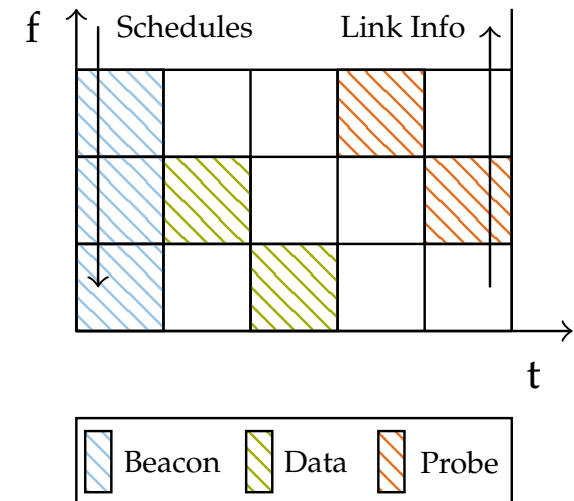
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Radio Resource Manager **outputs**:

1. Radio resources for Data packets (application).
2. Radio resources for Control packets (schedules, LQI probes, ...).

QoS Framework (2)

Dynamic scheduling is possible in a TDMA-FDMA radio resource grid model.



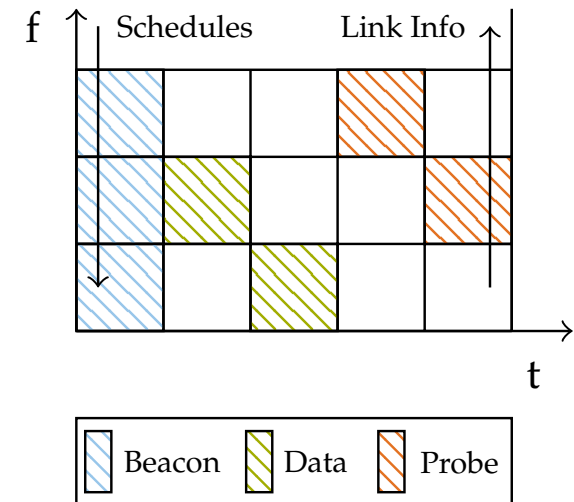
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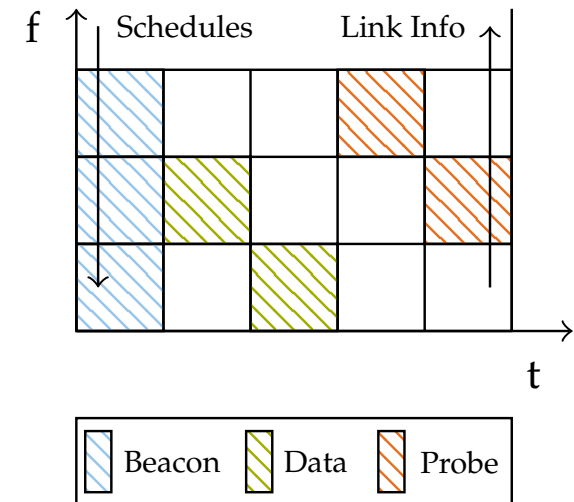
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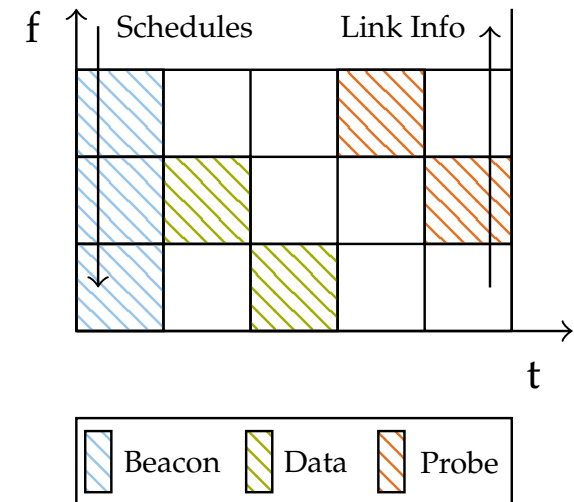
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3. Distribution of new schedules (**output**)
 - sequence of radio resources (time-freq. pairs)
 - distributed using the beacon
 - calculated with a **reliability-based scheduler**



Dynamic scheduling protocol.

QoS Framework (3) - Scheduling algorithm

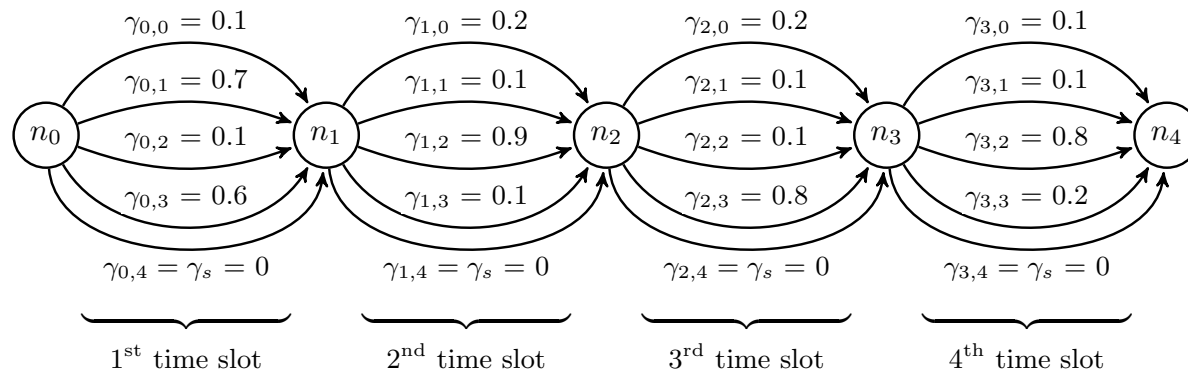
Reliability is provided allocating multiple transmissions in the frame.

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The radio resources are modeled using a **scheduling graph**:

- Nodes represent time instants before/after time slots.
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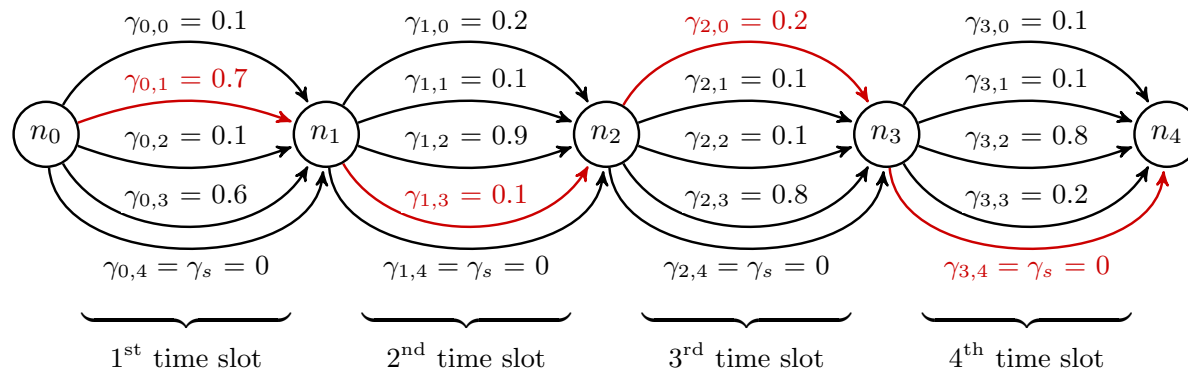
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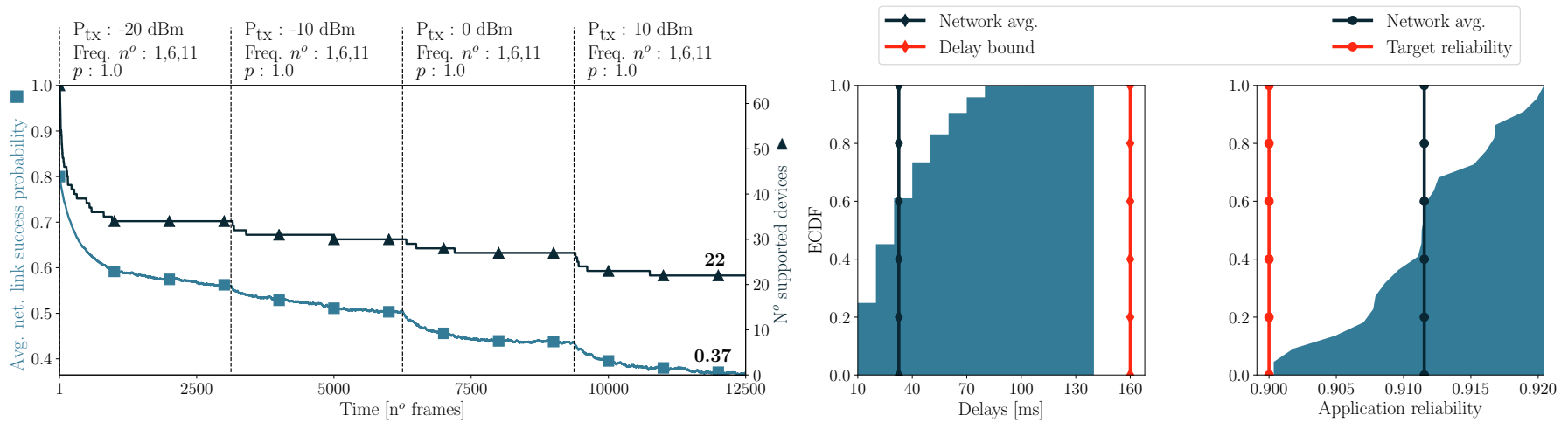
- Nodes represent time instants before/after time slots.
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A Constrained Shortest Path scheduling algorithm finds the **schedule** (path) fulfilling the **target reliability**. $\rightarrow \{(0, 1), (1, 3), (2, 0)\}$



QoS Framework (4) - Results

Simulation results of dynamic scheduling with latency and reliability constraints.

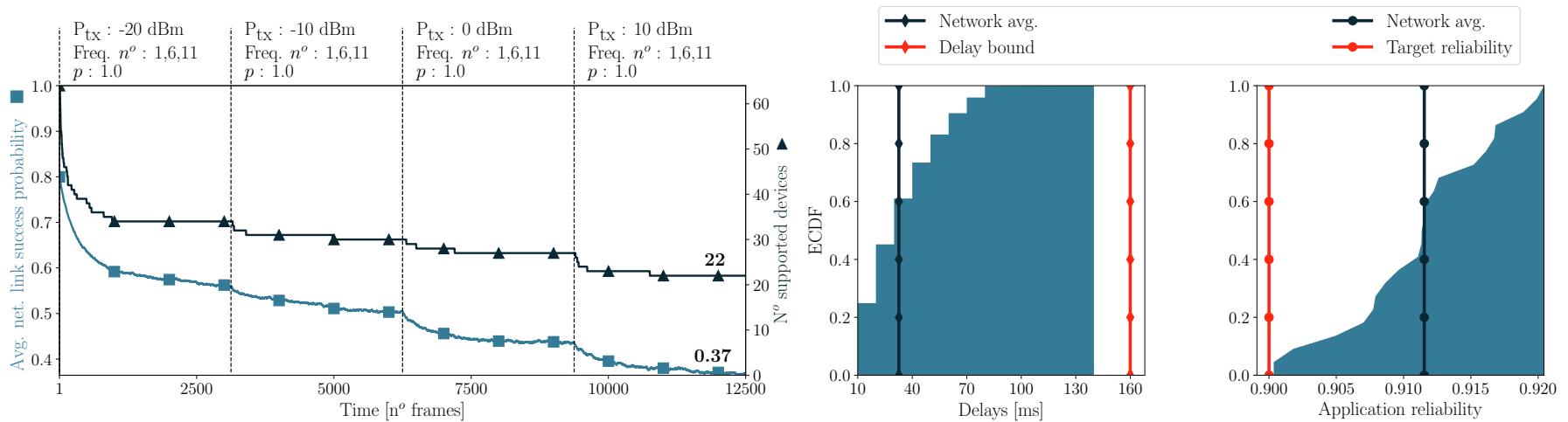


Reliability-based scheduling [eaED].

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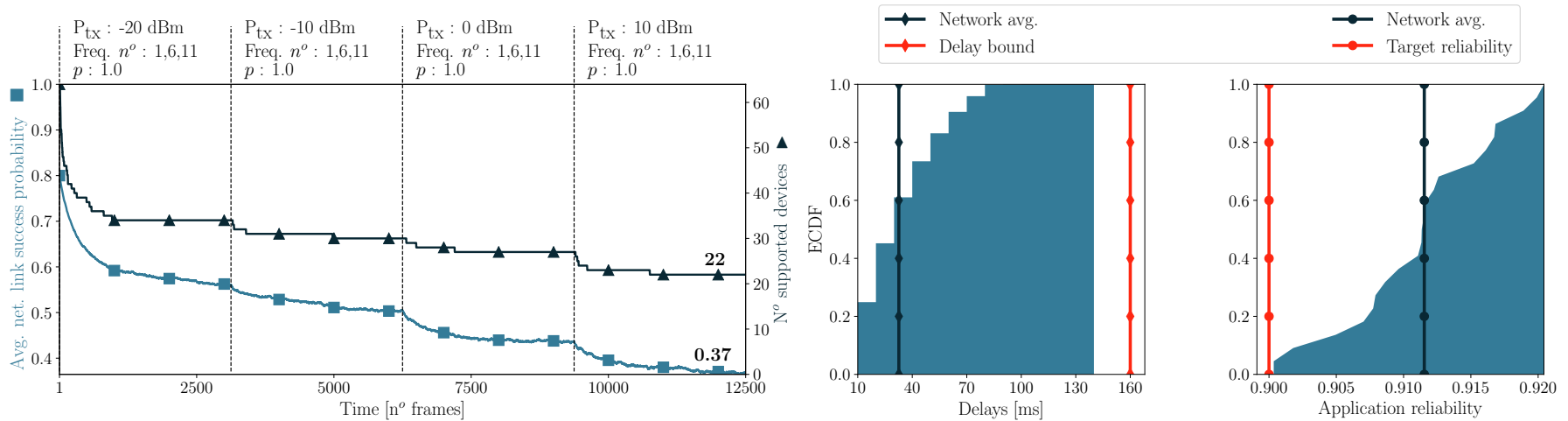
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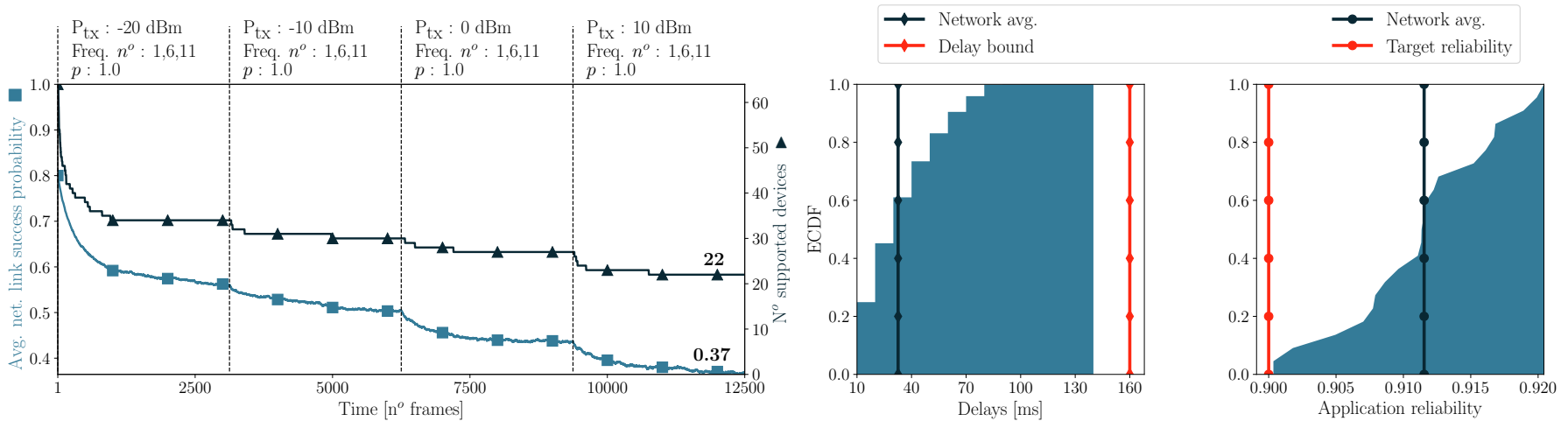
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WDetServ guarantees reliability and delay bounds reacting against interference.

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QoS Provisioning Framework

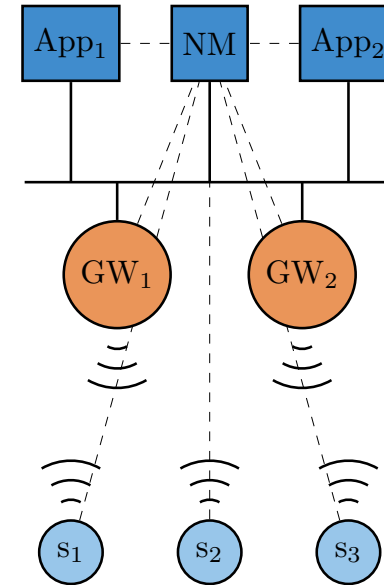
Implementation

Conclusions & Further Work

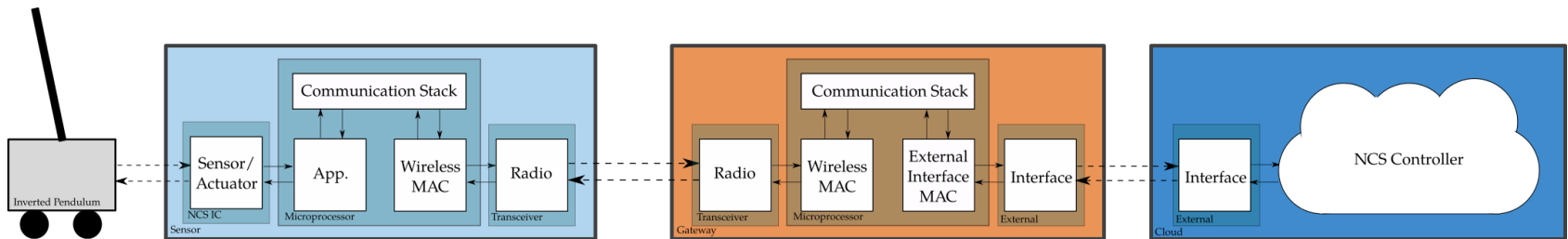
Implementation (1)

Deployment of an WDetServ NCS testbed:

1. Control logic (Controller) in the Cloud.
2. Sensing and Actuation in the WSN devices.
3. Gateway acts as forwarding entity.
4. Inverted Pendulum as benchmark control application.

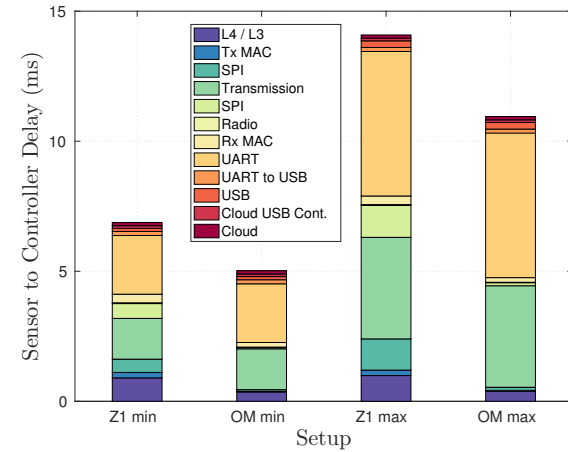


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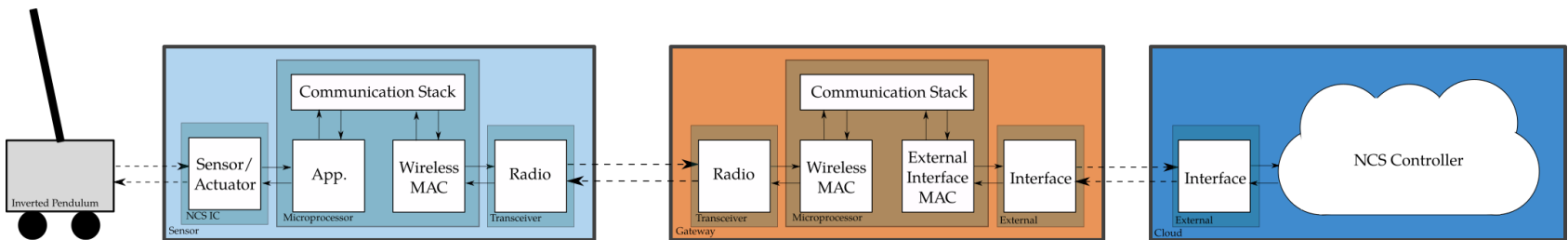


Implementation (2)

Problem: several HW and SW latency bottlenecks.



Sensor-to-cloud delay measurements[GZO⁺].

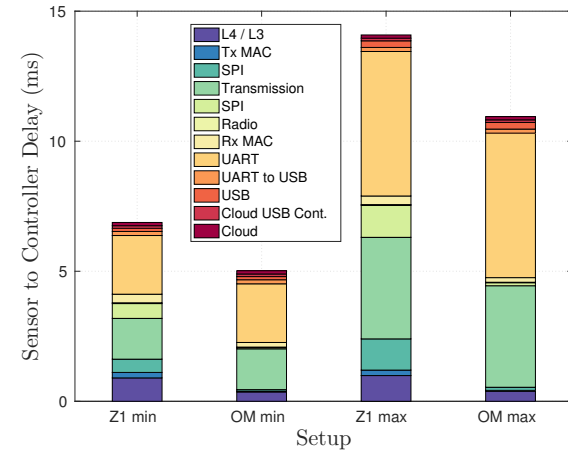


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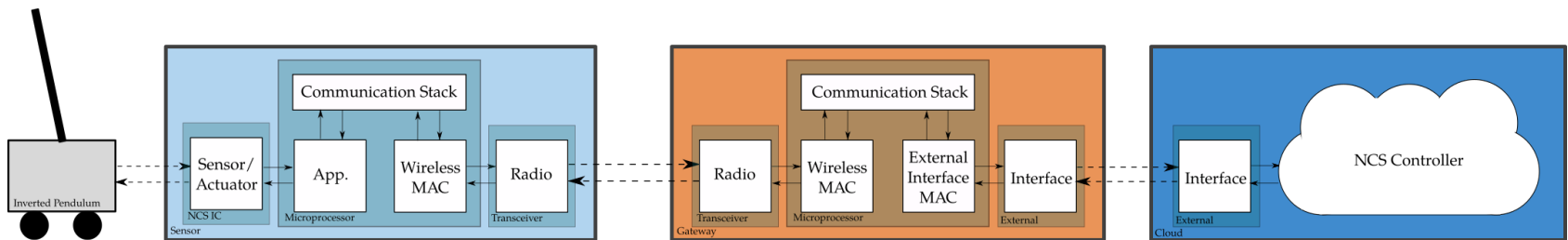
Problem: several HW and SW latency bottlenecks.

Solution: ad-hoc HW solutions for GW and WSN:

- Gateway
high perf., multi-radio, multi-processor
→ low-latency, multi-channel SDR
- Sensor
limited perf., single antenna, single processor
→ Zolertia Z1/RE-Mote, TI SimpleLink



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The implemented reliability-based scheduler is able to react to changes in the wireless environment.

Latency is the major issue for HW implementation (radio, processing, ext. interface).

Further Work





Measurements of NCS Inverted Pendulum operating over the testbed will be performed.

NCS cross-layer scheduling algorithms will be developed.

Different Link Quality Estimators will be evaluated in the testbed.

Multi-radio, multi-processor, high-speed interface solutions will be implemented.

References

-  [Samuele Zoppi et al.](#) Reliability-based scheduling for delay guarantees in hybrid wired-wireless industrial networks. *IEEE Transactions on Industrial Informatics*, SUBMITTED.
-  [M. Gürsu, M. Vilgelm, S. Zoppi, and W. Kellerer.](#) Reliable co-existence of 802.15.4e TSCH-based WSN and Wi-Fi in an aircraft cabin. In *2016 IEEE International Conference on Communications Workshops*, pages 663–668, May 2016.
-  [Halit Murat Gürsu, Samuele Zoppi, Hasan Yagiz Ozkan, Yadhunandana R. K., and Wolfgang Kellerer.](#) Tactile sensor to cloud delay: A hardware and processing perspective. In *IEEE ICC 2018 SAC Symposium Internet of Things Track (ICC'18 SAC-6 IoT)*, SUBMITTED.
-  [Mario Hermann, Tobias Pentek, and Boris Otto.](#) Design principles for industrie 4.0 scenarios. In *System Sciences (HICSS), 2016 49th Hawaii International Conference on*, pages 3928–3937. IEEE, 2016.