

The Role of Laser Ranging for the Global Geodetic Observing System GGOS

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The Global Geodetic Observing System (GGOS)

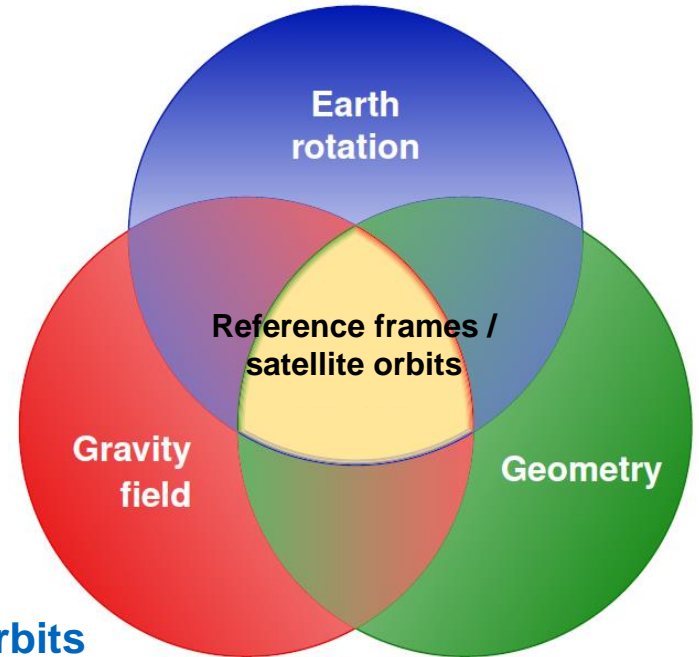
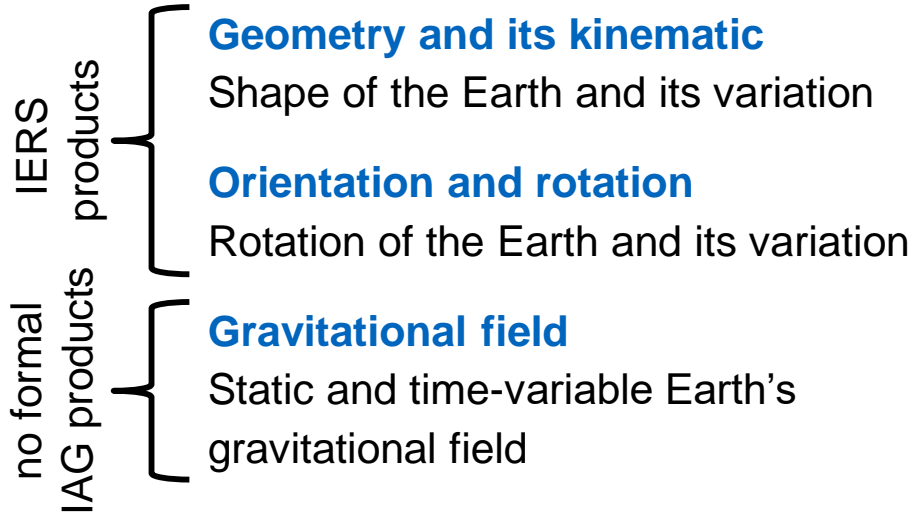
GGOS ...

- is the geodetic observing system of the **International Association of Geodesy** (IAG)
- focuses on **an order of magnitude improvement** in the quality of fundamental geodetic products (**essential geodetic variables**)
- supports the **improvement of the geodetic ground- and space-based infrastructure**
- **integrates** the geometric and gravimetric aspects of geodesy
- addresses important **geophysical questions** and **societal needs** (e.g., sea level rise / disaster management / natural hazards)

The main goal of GGOS is to provide **accurate geodetic products** with an accuracy of **1 mm** and **0.1 mm/yr** to the users

The Global Geodetic Observing System (GGOS)

➤ „3 pillars“ of geodesy:

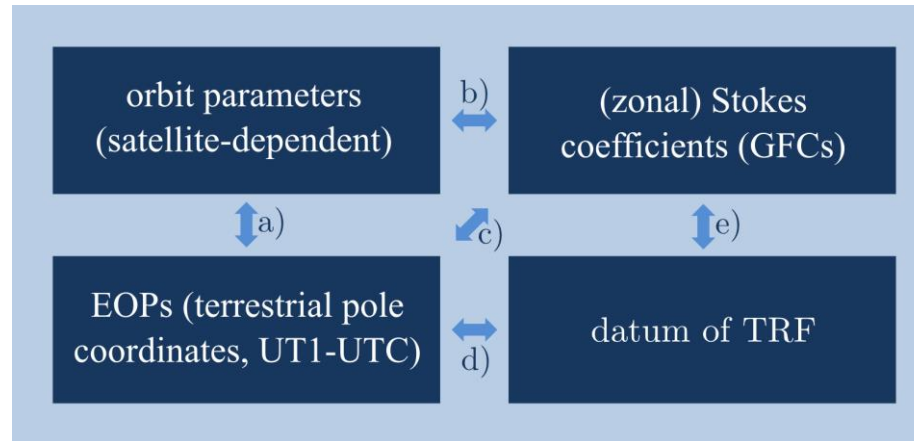


➤ Prerequisite for the integration:

highly accurate reference frames and satellite orbits

GGOS - challenges

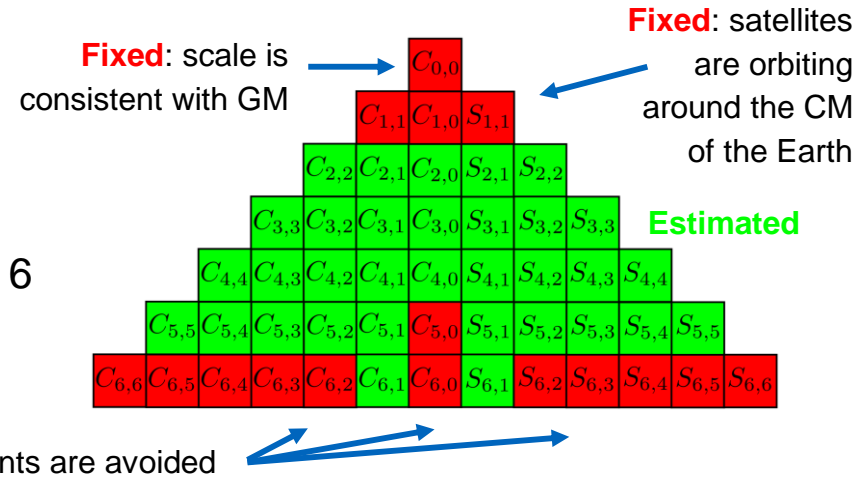
- non-common standards } **GGOS Bureau for Products and Standards (BPS)**
- inter-technique biases } **GGOS Bureau for Products and Standards (BPS)**
- non-homogeneous ground-based infrastructures } **GGOS Bureau for Networks and Observations (BNO)**
- high correlations between different parameter groups } **this talk**



[Bloßfeld et al., 2015]

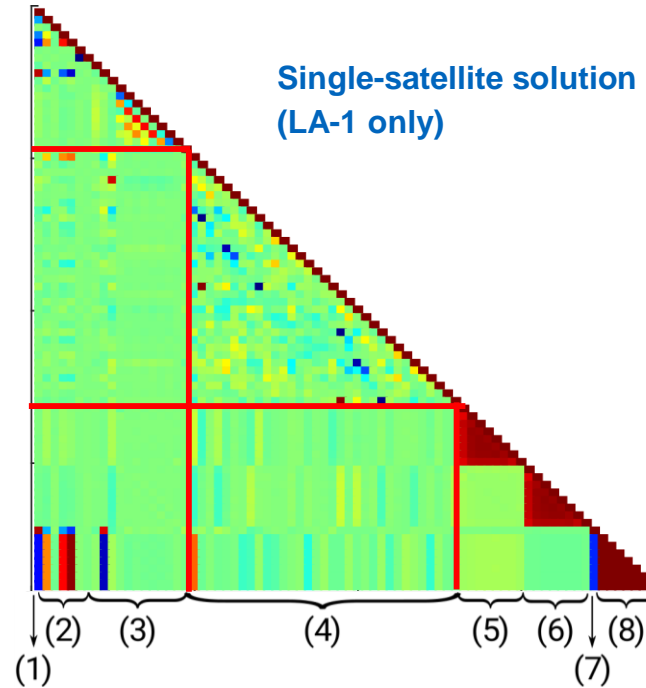
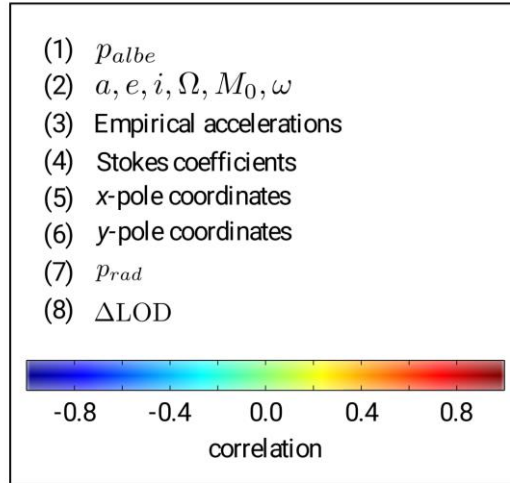
SLR – the tool to realize GGOS!

- SLR provides the ability to **study existing parameter correlations** since it is
 - sensitive to the reference frames (**TRF**) and **EOP**
 - sensitive to the long wavelengths of the **Earth's gravity field**
- **SLR multi-satellite constellation** solution can be used to evaluate potential
- Estimated parameters within this solution
 - Weekly 3-D station coordinates (TRF)
 - Daily Earth Rotation Parameter ($x_p, y_p, \Delta\text{LOD}$)
 - Weekly Stokes coefficients up to degree/order 6



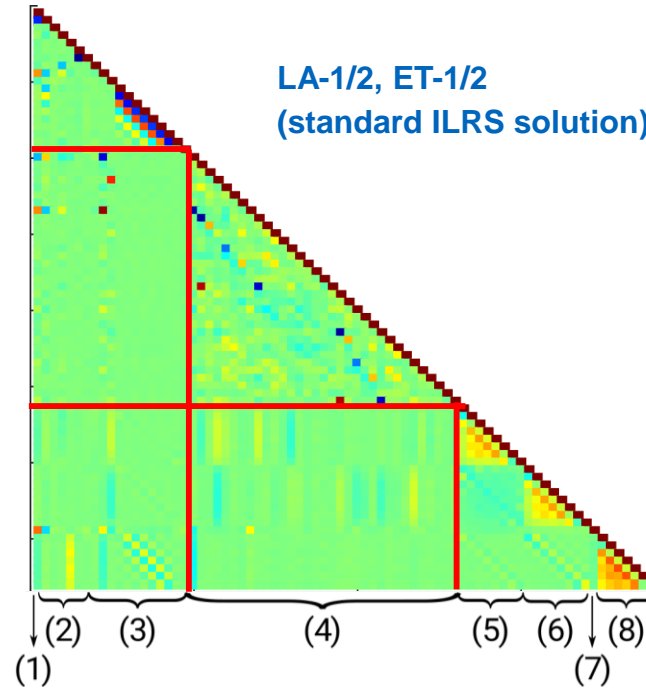
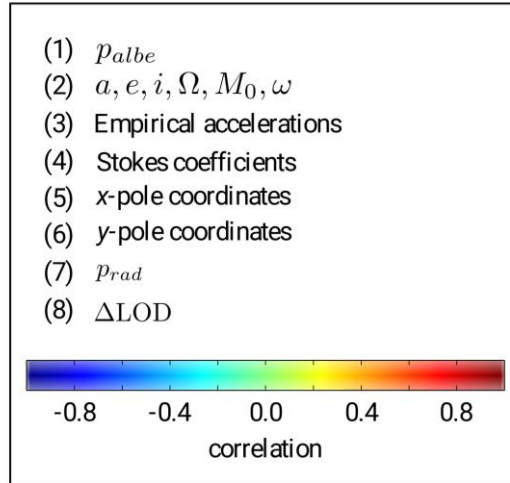
Parameter correlations

- Correlation matrix comprising orbit parameters (LA-1 only), GFC, and EOP (TRF not shown)



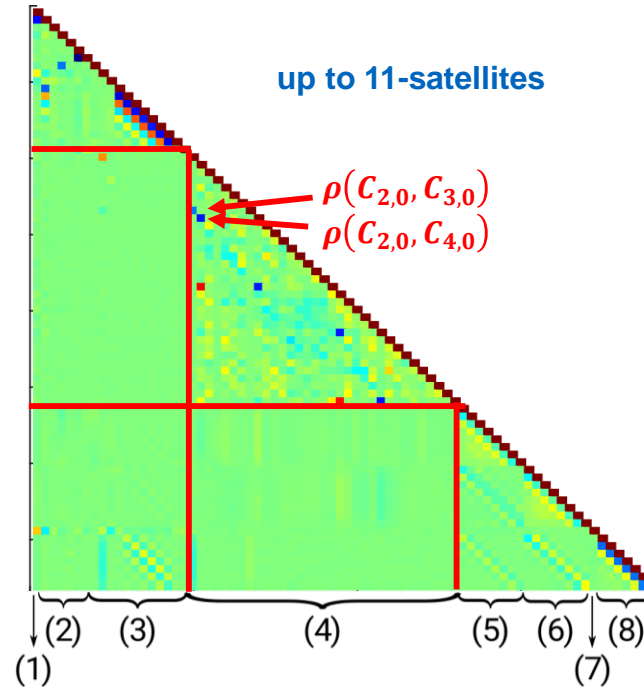
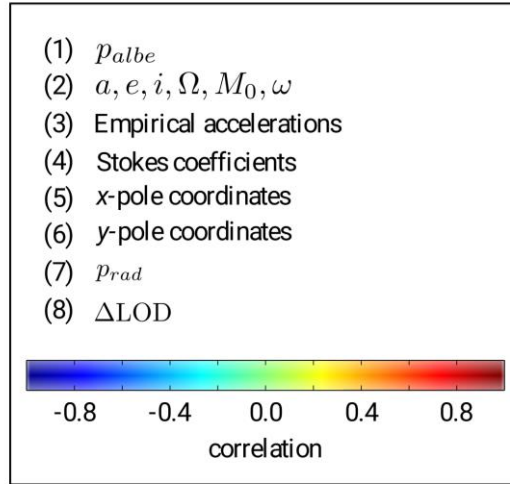
Parameter correlations

- Correlation matrix comprising orbit parameters (LA-1 only), GFC, and EOP (TRF not shown)



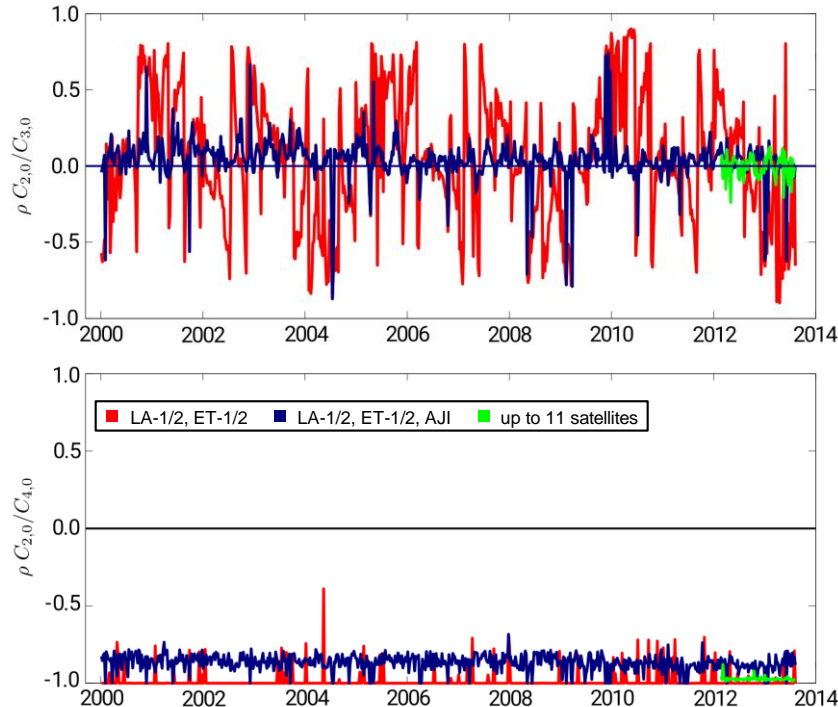
Parameter correlations

- Correlation matrix comprising orbit parameters (LA-1 only), GFC, and EOP (TRF not shown)



Parameter correlations

- Correlations between gravity field coefficients



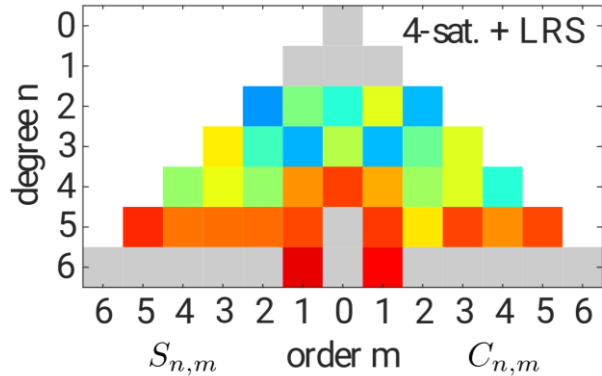
- $\rho(C_{2,0}, C_{3,0})$ can be stabilized significantly by using additional satellites.

- $\rho(C_{2,0}, C_{4,0})$ cannot be eliminated
- Reason: geometrical correlation of both coefficients

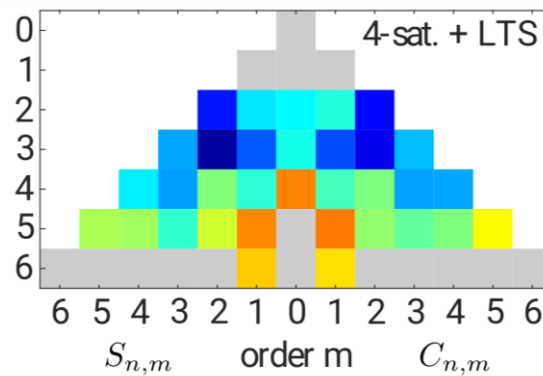
Results - gravity field

- Improvement of the mean WRMS values w.r.t. 4-satellite solution
 - 5-satellite solution: improvement patterns depending on the additional orbit
 - 11-satellite solution: individual improvement by **up to 93 %** (most valuable satellite: AJI)
 - average improvements:

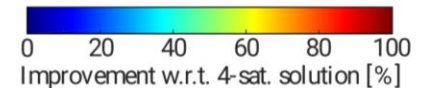
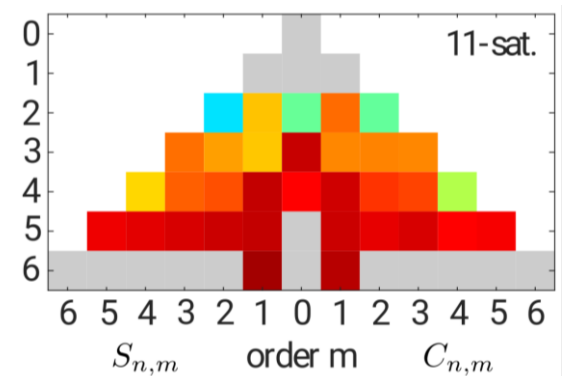
61.7 %



41.9 %

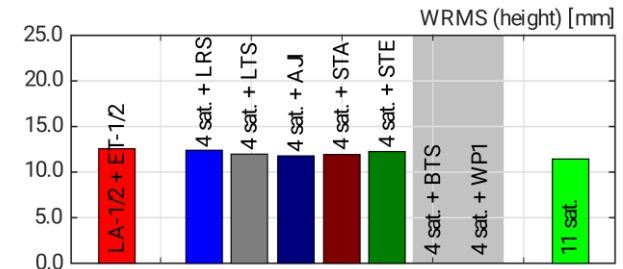
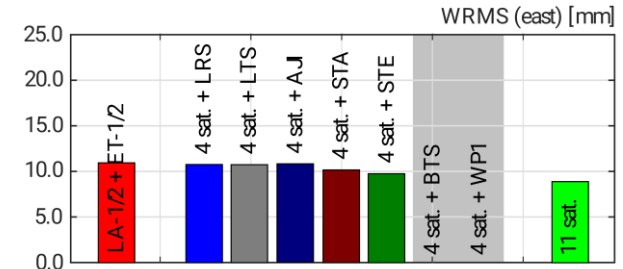
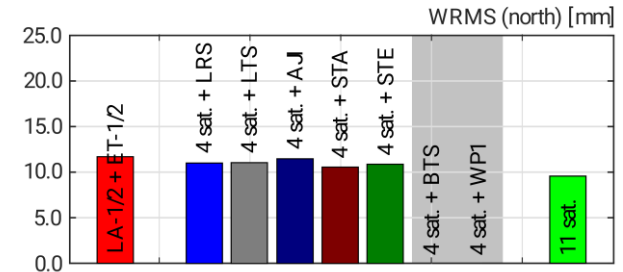
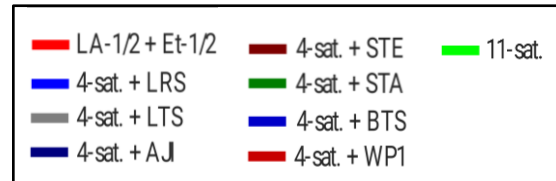


79.3 %



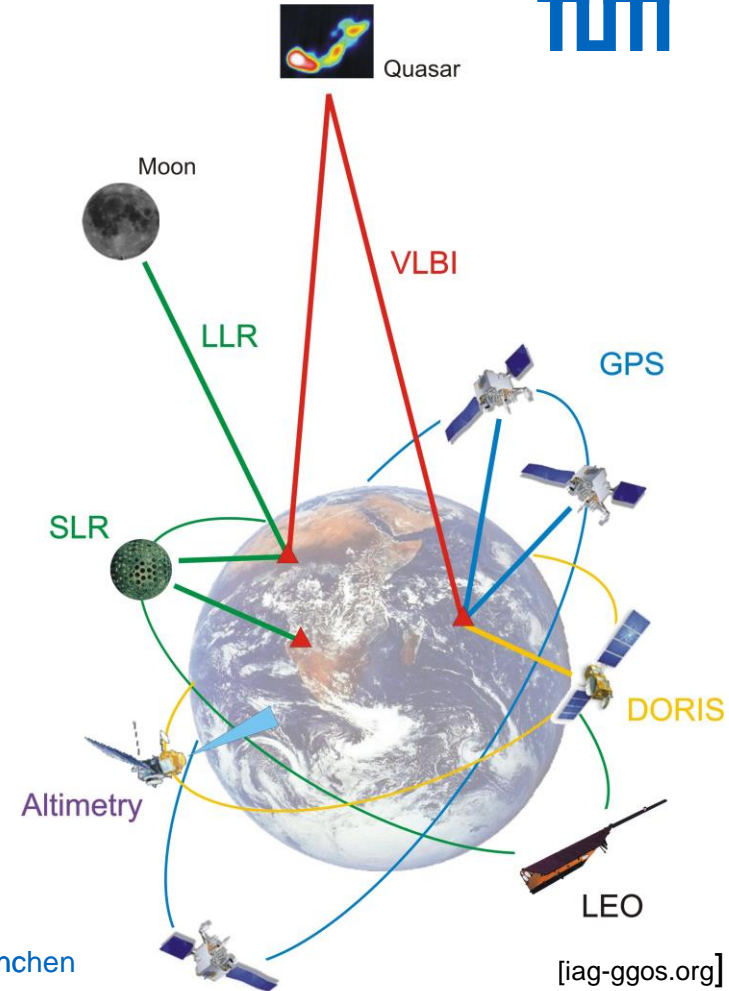
Results - TRF and ERP

- Weekly transformation w.r.t. SLRF2014
 - Max. reduction of scatter of TRF datum: **35 %**
 - Scatter of scale significantly **increased by AJI** due to CoM error
 - Station repeatability improved by up to **22 %**
- **ERP benefit similarly** from additional satellites
 - WRMS of the ERP reduced by up to **26 %**



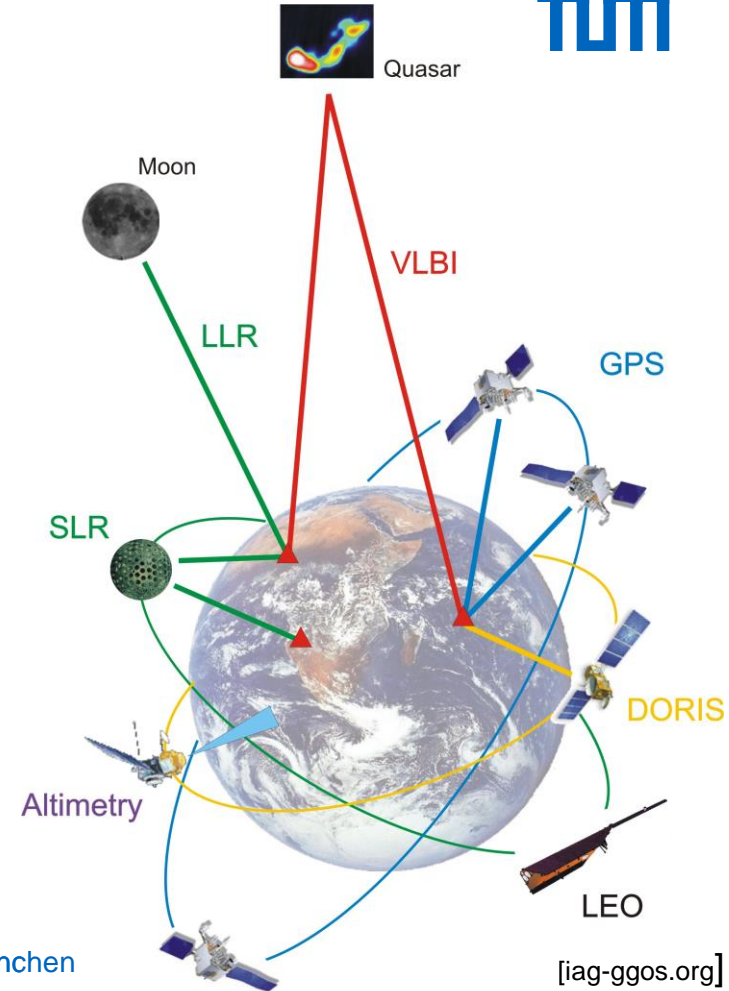
Conclusions

- GGOS aims the ambitious goal to **integrate geometric and gravimetric aspects** of modern space geodesy
- SLR is able to support this goal and to realize the GGOS vision
- Computing a multi-satellite multi-parameter solution allows to reduce parameter correlations
- **Gravity: up to 93 %, TRF: 22 - 35 %, EOP: 26 %**



Future steps

- Contribution to **IAG Services/components**
- Further research towards the **multi-technique multi-parameter solution**
- **Integration of diverse sensor-systems** into a global observing system (GGOS)
- **Improvement of the ground segment** (geometry and performances → see talks of A. Kehm)
- Support of **new mission proposals** (such as E-GRASP/E-MOTION)
- Usage of existing **space ties** (e.g., GNSS, SLR, DORIS on Jason-2)



Co-locations in space

- This potential is **not yet fully exploited**
- Problem: **Limited technique combinations** and **inadequate spacecraft calibrations**



Compass
GNSS/SLR



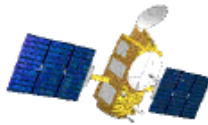
GLONASS
GNSS/SLR



GPS
GNSS/SLR



GIOVE/Galileo
GNSS/SLR



Jason
DORIS/GNSS/SLR



CHAMP
GNSS/SLR



Envisat
DORIS/SLR



GRACE
GNSS/SLR

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