

Fast Distributed Multi-Cell Scheduling with Delayed Limited-Capacity Backhaul Links

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Abstract—Both fast scheduling and spatial signal processing have proven to be capacity-increasing methods in wireless communication systems. However, when applied in the downlink of a cellular network, the combination of both leads to *non-stationary* intercell interference. If the base stations do not cooperate, either they have to encode the data very conservatively to gain robustness or the non-stationary fluctuations of the interference powers lead to frequent outages, both of which strongly impair the average achievable throughput. On the other hand, base station cooperation increases complexity and delays, contradicting the desire for *fast* scheduling algorithms. In this paper, we propose a scheme that makes *average* channel state information available to all base stations via *low-rate* backhaul communication, whereas *high-rate* inter-base-station communication is *limited* to $B \lceil \log_2 K \rceil$ -bit integers, K being the number of users in each of the B cells. Simulations show that for slow fading channels, the proposed algorithm preserves most of the per cell sum-rate of other beamforming and dirty-paper coding approaches that have *unlimited-capacity* backhaul links. Furthermore, when out-of-cell information is outdated the proposed algorithm even outperforms those.

I. INTRODUCTION

Cellular network architectures offer a great advantage which allows users to move freely within the coverage area without losing connections. When they leave the range of one base station, their signal is seamlessly “handed over” to another one. However, this freedom comes at the price of increased interference originating from neighboring cells operating in the same frequency bands for universal frequency reuse. While base stations can cooperatively process the transmitted signals of multiple users in a single cell, current network architectures do not allow for sophisticated cooperation *between* base stations. Consequently, algorithms that have proven to be very powerful in non-cellular networks, such as successive interference cancellation [1] or linear precoding [2], cannot easily be applied in cellular networks since the base stations lack common *channel state information* (CSI). Although, mathematically, a cellular system can be modeled as one “super cell” with spatially distributed antennas—recovering a standard *multiple input multiple output* (MIMO) system—the displacement of cooperative transmitters induces practical obstacles: how can shared data and CSI be made available to all base stations to make possible the implementation of techniques like *dirty paper coding* (DPC) [3]? Furthermore, the vast increases in data throughput and reliability that

temporal scheduling and *spatial precoding* offer when multiple transmit antennas are employed should still be utilized in multi-cell networks. However, they make *intercell interference* (ICI) non-stationary [4]; thus, the interference powers are different for each user and unpredictable for the base stations. This makes coordination between the base stations crucial and, accordingly, cooperation between base stations in the downlink of cellular MIMO systems has gained a lot of attention recently [5]–[15].

In this paper, we propose a scheduling and precoding scheme that makes the intercell interference powers of all users available to all base stations such that they can be taken into account when data is encoded. All computations and scheduling decisions are performed locally in a truly *distributed* fashion. The inter-base-station communication is *limited* to integers and may possibly be *delayed*. However, we assume that *average* CSI is available to all base stations. Multi-cell scheduling is a very active field of research [16]–[21], as is the analysis of limitations in the backhaul network connecting the base stations [22]–[27]. Our simulations show that the algorithm preserves most of the per cell sum-rate of the beamforming and dirty-paper coding approaches that require *unlimited-capacity* backhaul links and even outperforms them when out-of-cell information is outdated. A thorough problem formulation is presented in Section II before the proposed algorithm is presented and analyzed in Sections III and IV. Conclusions are drawn in the last section.

Notation: Vectors and matrices are denoted by bold lower and upper case letters, respectively. $\mathbb{E}[\bullet]$, j , $\mathbf{1}_M$, $\|\bullet\|_2$, $(\bullet)^*$, $(\bullet)^T$, and $(\bullet)^H$ denote expectation, imaginary unit, $M \times M$ identity matrix, Euclidean norm, complex conjugation, transposition, and conjugate transposition, respectively. e_i is the i -th column of $\mathbf{1}_M$, M given by the context.

II. SYSTEM MODEL AND PROBLEM FORMULATION

We consider the downlink of a cellular *multiple input single output* (MISO) system with B base stations each serving one of B cells. The K users in every cell cannot benefit from macro-diversity offered through adjacent base stations. At any given time slot n , only one user is active per cell; it is allocated the total transmit power E_{tr} that a base station can allocate to its N_a transmit antennas. This user is independently selected for each cell b by a local (non-centralized) *proportional-fair*

scheduler (PFS), which weights the data stream $s_{b,k}[n] \in \mathbb{C}$ with $\sqrt{P_{b,k}^{[m]}} = \sqrt{E_{\text{tr}}}$, if the k -th user in cell b is scheduled, and otherwise with $\sqrt{P_{b,k}^{[m]}} = 0$. The scheduling decisions are assumed to be synchronized among the base stations and are labeled with the time index $[m]$ such that we have two different time scales, $[n]$ for the symbols and $[m]$ for “packets”. Every user may have its own unit-norm precoding vector $\mathbf{t}_{b,k}^{[m]} \in \mathbb{C}^{N_a}$ such that the transmitted signal of the b' -th base station, which traverses the slow fading vector channel $\mathbf{h}_{b,k,b'}^{[m]} \in \mathbb{C}^{N_a}$ to user k in cell b , is $\mathbf{x}_{b'}[n] = \sqrt{E_{\text{tr}}}\mathbf{t}_{b',\hat{k}}^{[m]}s_{b',\hat{k}}[n] \in \mathbb{C}^{N_a}$, where \hat{k} is the user that is served in each cell. The signal $\hat{s}_{b,k}[n] \in \mathbb{C}$ that the k -th user in the b -th cell receives is then given by

$$\begin{aligned} \hat{s}_{b,k}[n] &= \mathbf{h}_{b,k,b}^{[m],T} \mathbf{t}_{b,\hat{k}}^{[m]} \sqrt{E_{\text{tr}}} s_{b,\hat{k}}[n] \\ &+ \sum_{\substack{b'=1 \\ b' \neq b}}^B \mathbf{h}_{b,k,b'}^{[m],T} \mathbf{t}_{b',\hat{k}}^{[m]} \sqrt{E_{\text{tr}}} s_{b',\hat{k}}[n] + \eta_{b,k}[n]. \end{aligned}$$

$\eta_{b,k}[n]$ is a *stationary* zero-mean additive white Gaussian noise process with variance σ_{η}^2 .

Because of the fast scheduling at the base stations, the precoders vary quickly in time. As a direct consequence, the transmit covariance matrices (which have rank 1 since only one user is active per cell)

$$\begin{aligned} \mathbf{Q}_b^{[m]} &:= \mathbb{E} \left[\mathbf{x}_b[n] \mathbf{x}_b^H[n] \middle| \left\{ P_{b,i}^{[m]}, \mathbf{t}_{b,i}^{[m]} \right\}_{i=1}^K \right] \\ &= \sum_{i=1}^K P_{b,i}^{[m]} \mathbf{t}_{b,i}^{[m]} \mathbf{t}_{b,i}^{[m],H} = E_{\text{tr}} \mathbf{t}_{b,\hat{k}}^{[m]} \mathbf{t}_{b,\hat{k}}^{[m],H} \end{aligned} \quad (1)$$

and the intercell-interference-plus-noise powers

$$\begin{aligned} \sigma_{i_b,k}^2[m] &= \mathbb{E} \left[|i_{b,k}[n]|^2 \middle| \left\{ P_{b',i}^{[m]}, \mathbf{t}_{b',i}^{[m]} \right\}_{b'=1, b' \neq b, i=1}^{B,K} \right] \\ &= \sigma_{\eta}^2 + \sum_{\substack{b'=1 \\ b' \neq b}}^B \mathbf{h}_{b,k,b'}^{[m],T} \mathbf{Q}_{b'}^{[m]} \mathbf{h}_{b,k,b'}^{[m],*} \end{aligned} \quad (2)$$

vary quickly over time as well. Here, we assume *independent and identically distributed* (i.i.d.) *stationary* Gaussian symbols $s_{b,k}[n]$ with zero mean and unit variance, such that the additive noise plus intercell interference $i_{b,k}[n]$ for user k in cell b , viz.,

$$i_{b,k}[n] = \eta_{b,k}[n] + \sum_{\substack{b'=1 \\ b' \neq b}}^B \sum_{i=1}^K \mathbf{h}_{b,k,b'}^{[m],T} \mathbf{t}_{b',i}^{[m]} \sqrt{P_{b',i}^{[m]}} s_{b',i}[n], \quad (3)$$

is Gaussian distributed (for fixed m) with zero mean and variance $\sigma_{i_b,k}^2[m]$. Since the maximal achievable rate in cell b is given by

$$R_b^{[m]} = \log_2 \left(1 + \frac{\mathbf{h}_{b,\hat{k},b}^{[m],T} \mathbf{Q}_b^{[m]} \mathbf{h}_{b,\hat{k},b}^{[m],*}}{\sigma_{i_b,\hat{k}}^2[m]} \right) \quad (4)$$

it depends on all transmit covariance matrices $\{\mathbf{Q}_b^{[m]}\}_{b=1}^B$ in the entire network (cf. (2)). If the base stations do not

cooperate, they have no means to predict $\sigma_{i_b,k}^2[m]$ for the next transmission frame and system performance will suffer in terms of sum-rate and outage [4].

Ultimately, one is interested in jointly optimizing all transmit covariance matrices $\{\mathbf{Q}_b^{[m]}\}_{b=1}^B$ in the entire network in order to maximize the sum-network capacity, i.e., the supremum of all achievable rates $\sum_{b=1}^B R_b^{[m]}$. As an intermediate step, system performance could considerably be improved by eliminating the blindness towards $\sigma_{i_b,k}^2[m]$ at base station b , which in theory could be accomplished by an infinite-capacity, delay- and error-free backhaul network connecting all base stations. However, in practice, backhaul communication is always compromised by delays, errors, and finite capacity links. In this work, we still make the assumption of error-free backhaul communication, yet we allow for non-zero delays and limited capacity. These limitations are especially crucial in mobile telecommunications standards such as 1xEVDO, 3GPP LTE, or WiMax, where the scheduling occurs at a high frequency. Fast fluctuations in $\sigma_{i_b,k}^2[m]$ are desired, for they allow to harness multi-user diversity, but are detrimental when the base stations are blind to them. Hence, the goal is to preserve the fast fluctuations while removing the blindness with respect to the intercell interference powers $\sigma_{i_b,k}^2[m]$.

We assume that the b -th base station knows the vector channels $\{\mathbf{h}_{b,k,b'}^{[m]}\}_{b'=1}^B$ for all k . This is *local* CSI only, so no base station cooperation or central processing is required. While the assumption of perfect CSI may be unrealistic, it is justified, for our goal is the analysis of communication *between* base stations. Furthermore, our assumption is far less restrictive than assuming ubiquitous CSI (all base stations know all $\mathbf{h}_{b,k,b'}^{[m]}$). As (2) indicates, based on that premise, the uncertainty in $\sigma_{i_b,k}^2[m]$ actually is an uncertainty in $\{\mathbf{Q}_{b'}^{[m]}\}_{b'=1}^B$. As mentioned earlier, distributed knowledge of $\{\mathbf{Q}_b^{[m]}\}_{b=1}^B$ is unreasonable as it requires the exchange of $B \times N_a$ complex coefficients. Therefore, we aim at an algorithm that can make all $\{\mathbf{Q}_b^{[m]}\}_{b=1}^B$ available to all base stations within milliseconds through (limited capacity) backhaul links while preserving the fast changes in $\{\mathbf{Q}_b^{[m]}\}_{b=1}^B$.

III. PROPOSED ALGORITHM

Based on the *local* channel information $\{\mathbf{h}_{b,k,b'}^{[m]}\}_{b'=1}^B$, each base station can independently compute the eigenvalue decomposition of an estimate of the channel covariance matrix

$$\mathbf{R}_{b,k,b} = \frac{1}{N_T} \sum_{m=1}^{N_T} \mathbf{h}_{b,k,b}^{[m]} \mathbf{h}_{b,k,b}^{[m],H} = \sum_{\zeta=1}^{N_a} \xi_{b,k,b,\zeta} \mathbf{q}_{b,k,b,\zeta} \mathbf{q}_{b,k,b,\zeta}^H$$

and then choose the conjugate complex of the principal eigenvector of user k as its precoder, viz., $\mathbf{t}_{b,k}^{[m]} = \mathbf{q}_{b,k,b,1}^*$, $\xi_{b,k,b,1} \geq \xi_{b,k,b,2} \geq \dots \geq \xi_{b,k,b,N_a} \geq 0$. Because $\mathbf{R}_{b,k,b}$ depends on the topology of the network, $\mathbf{q}_{b,k,b,1}$ varies very slowly over time and a low-rate backhaul link is sufficient to distribute the $\mathbf{t}_{b,k}^{[m]}$ to all base stations. This eliminates all uncertainty in $\{\mathbf{Q}_b^{[m]}\}_{b=1}^B$, which all base stations can now

independently compute through (1) with $P_{b,k}^{[m]} = E_{\text{tr}}$ if $k = \hat{k}$ and $P_{b,k}^{[m]} = 0$ otherwise ($b = 1, \dots, B$) if they know \hat{k} for all b . Fortunately, \hat{k} is integer with only $\lceil \log_2 K \rceil$ bits word length, such that a finite capacity link suffices to distribute the B integers \hat{k} to all base stations.

The \hat{k} are determined locally in a distributed fashion by a PFS in two phases, the first of which we call ‘‘prescheduling’’. There is no centralized scheduling or processing. The *prescheduler* determines *which precoding vector* each base station will apply; the actual *scheduler* (phase II) then schedules *which user* will be served in the next time frame *with the precoder from phase I, thus leaving the ICI powers (2) unchanged*. The proportional fair scheduling is based on the following three quantities:

- 1) the estimated supported data rate for user k in cell b :

$$R_{b,k}^{\text{I},[m]} = \log_2 \left(1 + \frac{E_{\text{tr}} \left| \mathbf{h}_{b,k,b}^{[m],\text{T}} \mathbf{t}_{b,k}^{[m]} \right|^2}{\sigma_{b,k}^2 [m-1]} \right) \quad (5)$$

- 2) the actual supported data rate for user k in cell b :

$$R_{b,k}^{\text{II},[m]} = \log_2 \left(1 + \frac{E_{\text{tr}} \left| \mathbf{h}_{b,k,b}^{[m],\text{T}} \mathbf{t}_{b,\hat{k}}^{[m]} \right|^2}{\sigma_{\eta}^2 + E_{\text{tr}} \sum_{b' \neq b}^B \left| \mathbf{h}_{b,k,b'}^{[m],\text{T}} \mathbf{t}_{b',\hat{k}}^{[m]} \right|^2} \right) \quad (6)$$

- 3) the average throughput $\bar{R}_{b,k}^{[m]}$ of user k in cell b which is updated after each packet via (cf. (4))

$$\bar{R}_{b,k}^{[m]} = \begin{cases} (1-f)\bar{R}_{b,k}^{[m-1]} + fR_b^{[m-1]} & k = \hat{k} \\ (1-f)\bar{R}_{b,k}^{[m-1]} & k \neq \hat{k} \end{cases}, \quad \forall b.$$

f is called the *forgetting factor* which ranges from 0 to 1. For $f \rightarrow 1$, the PFS approaches the *round robin scheduler*, and for $f \rightarrow 0$, the PFS approaches the *greedy scheduler*. Hence, the forgetting factor can be used to tune the scheduler between maximum throughput/multi-user diversity and fairness/delay. For more details, see [28].

First, the prescheduler determines *locally*, which precoder base station b is going to apply by

$$\check{k} = \operatorname{argmax}_{k=1,\dots,K} \frac{R_{b,k}^{\text{I},[m]}}{\bar{R}_{b,k}^{[m]}} \quad \forall b. \quad (7)$$

\hat{k} is then obtained locally at the b -th base station by evaluating

$$\hat{k} = \operatorname{argmax}_{k=1,\dots,K} \frac{R_{b,k}^{\text{II},[m]}}{\bar{R}_{b,k}^{[m]}} \quad \forall b. \quad (8)$$

\hat{k} is the user that is actually served by the b -th base station. However, $\mathbf{t}_{b,\hat{k}}^{[m]} = \mathbf{q}_{b,\hat{k},b,1}^*$ is not necessarily the precoder, that this base station employs to serve user \hat{k} . Rather, each base station has to employ the precoder $\mathbf{t}_{b,\hat{k}}^{[m]} = \mathbf{t}_{b,\hat{k}}^{[m]}$ that was determined by the prescheduler in (7) as \check{k} is the information that is broadcasted to all base stations and hence, all base stations compute their estimates of the intercell interference based on

the assumption that $\hat{k} = \check{k}$. However, while that may not be the case in reality, this mismatch does not affect $\{\mathbf{Q}_b^{[m]}\}_{b=1}^B$ as $\mathbf{t}_{b,\hat{k}}^{[m]} = \mathbf{t}_{b,\check{k}}^{[m]} \forall b$, viz., user \hat{k} is served by the principal eigenvector belonging to the channel covariance matrix of user \check{k} . The difference between the two schedulers is that the prescheduler in phase I only relies on local channel state information, and accordingly does not require any inter-base-station communication. The second scheduler, that determines the user \hat{k} served in cell b at slot m , on the other hand does require information from other base stations, namely the $\lceil \log_2 K \rceil$ -bit integers, which have to be distributed to all base stations between the two scheduling procedures. *However, it does not change the ICI powers (2).*

IV. SIMULATION RESULTS

For our simulations, we assume a *sectorized* cellular layout, i.e., three base stations are co-located at the vertices of three cells (see [4], [11]). The users are uniformly distributed within the area of a cell. We model the coefficients $e_{\zeta}^{\text{T}} \mathbf{h}_{b,k,b'}^{[m]}$, $\zeta = 1, \dots, N_a$, of the vector channels $\mathbf{h}_{b,k,b'}^{[m]} \in \mathbb{C}^{N_a}$ by

$$e_{\zeta}^{\text{T}} \mathbf{h}_{b,k,b'}^{[m]} = \sum_{\ell=1}^M \sqrt{\frac{\rho(d_{b,k,b'}, \theta_{b,k,b'} + \varphi_{\ell})}{M}} \times \exp \{ j [\pi(\zeta - 1) \sin(\theta_{b,k,b'} + \varphi_{\ell}) + \psi_{b,k,b',\ell}] \} \times \exp \{ j 2\pi f_{\text{D}} \cos(\beta_{b,k}) m / f_{\text{slot}} \},$$

where φ_{ℓ} models the angular spread of M unresolvable sub-paths. We assume $M = 20$ and take φ_{ℓ} as specified in the 3GPP Spatial Channel Model for MIMO simulations [29]. The function $\rho(d, \theta)$ incorporates the maximum antenna gain in boresight direction $\hat{A} = 14\text{dBi}$, the path-loss, the log-normal shadowing, and the antenna beam pattern $A(\theta)$ (cf. [4], [29]), and is given by

$$\rho(d, \theta) = 10^{0.1\hat{A}} \cdot \left(\frac{\lambda}{4\pi} \right)^2 \cdot d^{-\gamma} \cdot 10^{0.1\chi} \cdot 10^{0.1A(\theta)},$$

where $\lambda = 15\text{cm}$ and $\gamma = 3.8$ are the carrier wavelength and the path-loss exponent, respectively. χ is Gaussian distributed with zero mean and variance 36, and $\psi_{b,k,b',\ell}$ is uniformly distributed in $[-\pi, \pi]$. $d_{b,k,b'}$ and $\theta_{b,k,b'}$ are the distance and the angle to base station b' (with respect to its boresight direction) for the k -th user in cell b , respectively. $f_{\text{D}} = v/\lambda$, $f_{\text{slot}} = 1500\text{Hz}$, and $\beta_{b,k}$ are the maximum Doppler frequency at velocity v , the slot rate, and the velocity angle, respectively ($\beta_{b,k} \sim \mathcal{U}(-\pi, \pi)$). In order to not violate the far-field assumption, we also have $\min d_{b,k,b'} \geq 200\lambda$. The remaining simulation parameters are $B = 57$, $K = 6$, $N_a = 4$, $\sigma_{\eta}^2 = -100.8\text{dBm}$, and $E_{\text{tr}} = 10W$. The distance between base stations is 2km.

Figure 1 compares the cumulative distribution functions of our proposed scheduler (called *cooperative eigenbeamforming* or CEB) to other multi-cell scheduling and precoding algorithms for R_{30} , $b = 30$ being the cell of interest in the center of the network [4]. One can see that in this scenario, where we assume no mobility ($v = 0$), a small angular spread

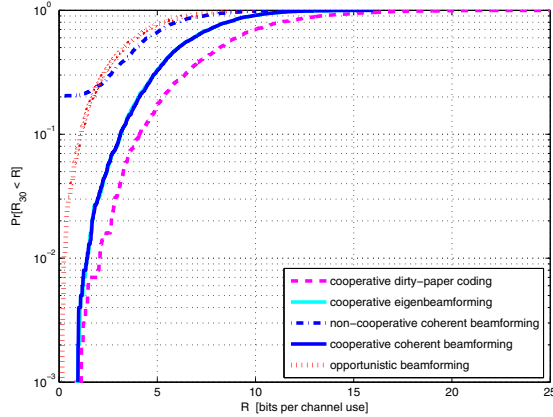


Fig. 1. Cumulative distribution functions of various schemes for no mobility, small angular spread, and greedy schedulers.

($\delta = 2^\circ$) and a greedy scheduler ($f \rightarrow 0$), *cooperative dirty-paper coding* is the only algorithm that performs better than the proposed approach. Note, however, that cooperative DPC requires the knowledge of all $B \times B \times K \times N_a$ complex channel coefficients at all base stations, whereas our algorithm simply distributes B integers! A detailed description of cooperative DPC can be found in [11], where it is called the “genie approach”. *Opportunistic beamforming* is described in [4] and does not require any channel knowledge, but it also performs worse than CEB. For the chosen scenario here, *cooperative coherent beamforming* (CCB) performs as well as cooperative eigenbeamforming (the two curves overlap). Cooperative coherent beamforming uses the same two-phase scheduler as cooperative eigenbeamforming but requires the knowledge of all $B \times K$ vector channels $\mathbf{h}_{b,k}^{[m]}$ at all base stations to apply $\mathbf{t}_{b,k}^{[m]} = \mathbf{h}_{b,k,b}^{[m],*} / \|\mathbf{h}_{b,k,b}^{[m]}\|_2$ in (5) and (6). Last but not least, huge losses are observed for *non-cooperative coherent beamforming*, where base stations do not cooperate, that is, only the prescheduler is employed and

$$R_{30} = \begin{cases} R_{30,\check{k}}^{I,[m]} & R_{30,\check{k}}^{I,[m]} \leq R_{30}^{[m]} \\ 0 & \text{otherwise.} \end{cases}$$

In the sequel, we only compare CCB and CEB for different forgetting factors, angular spreads, and delays in the backhaul network. Figure 2 depicts the average throughput in cell $b = 30$ for different forgetting factors and angular spreads at $v = 0$. For an angular spread of $\delta = 2^\circ$, CEB performs nearly as well as CCB. Only for large angular spreads ($\delta = 35^\circ$) does the principal component not suffice to model the spatial correlations, as the M sub-paths are too widely spread in space. Furthermore, as f increases from 0 to 1, the system can harness less and less multi-diversity as the PFS enforces more and more fairness. Hence, the average throughput declines.

Let us now examine the impact of delays in the backhaul network that may arise from processing or propagation. In particular, while the numerator in (6) remains unchanged, for it only depends on local CSI, we replace $\mathbf{t}_{b',\check{k}}^{[m]}$ with $\mathbf{t}_{b',\check{k}}^{[m-2]}$ in the denominator of (6) assuming a delay of 2 time slots.

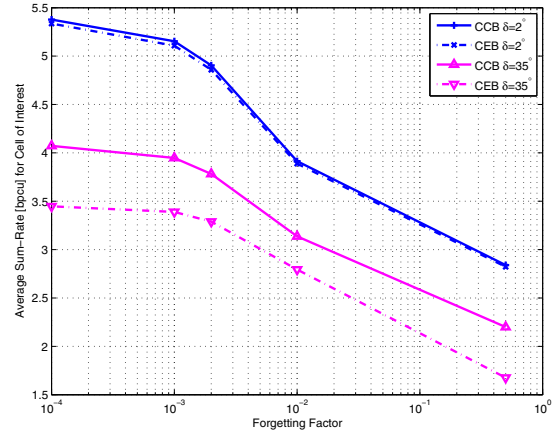


Fig. 2. Comparison of CCB and CEB for different forgetting factors and angular spreads without user mobility ($v = 0$).

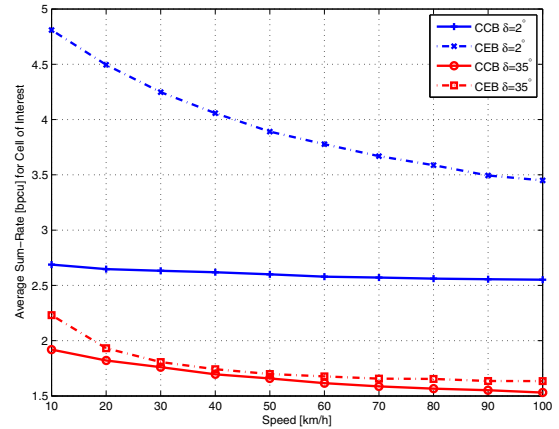


Fig. 3. Impact of outdated CSI due to Doppler shifts.

$\mathbf{t}_{b',\check{k}}^{[m-2]}$ may differ from $\mathbf{t}_{b',\check{k}}^{[m]}$ for two reasons which we will examine separately. Figure 3 depicts the case where $\mathbf{h}_{b,k,b'}^{[m]}$ has changed due to mobility in the network. To mask the impact of the schedulers, i.e., changes in \check{k} , we use a greedy scheduler. From Fig. 3, we observe that CEB has a considerable gain over CCB when backhaul communication is delayed. Because the precoders of CEB mainly depend on spatial properties of the network and thus are time-independent, it features strong robustness towards Doppler shifts arising from user mobility. That gain is so large that even for large angular spreads, CEB now outperforms CCB. In Fig. 4, we assume constant channels ($v = 0$) and examine the impact of the schedulers, i.e., changes in \check{k} , on the average throughput for delayed backhaul communication. One can observe the following: First, CEB and CCB have comparable performance, especially for small angular spreads. Second, the average throughput of both schemes is substantially impaired as compared to the results shown in Fig. 2. Third, as f increases, the system can harness less and less multi-user diversity and accordingly, the average throughput decreases. But as the PFS approaches the round robin scheduler ($f \rightarrow 1$), the base stations increasingly

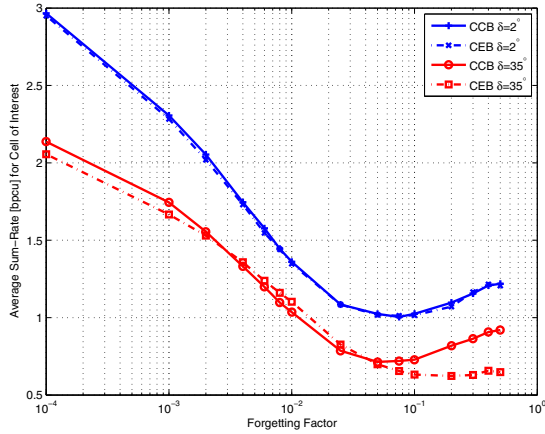


Fig. 4. Impact of outdated scheduling decisions without user mobility.

schedule a different user at each time slot. Because the ICI (3) is the superposition of $B - 1 = 56$ cells, averaging takes place and the dynamics of (2) decrease, resulting in fewer outages and larger average throughputs. In other words, on average, when $R_{30, \hat{k}}^{II, [m]}$ was achievable, i.e., $R_{30, \hat{k}}^{II, [m]} \leq R_{30}^{[m]}$, R_{30} is still smaller for larger f ; however, as f increases, fewer outages (viz. $R_{30} = 0$ since $R_{30, \hat{k}}^{II, [m]} > R_{30}^{[m]}$ was not achievable) occur due to the averaging and the sum-rate increases on average. Because CEB operates with a single principal direction per cell, the averaging is more pronounced for CCB which knows the angular spread due to local CSI.

V. CONCLUSIONS

We introduced a scheduler for cellular networks that removes all blindness with respect to interference powers, such that the base stations can encode the data much more accurately and outages are considerably reduced. All computations including the scheduling are performed locally at each base station. The algorithm requires low-rate communication between base stations to distribute average CSI. However, high-rate backhaul communication is limited to $B \lceil \log_2 K \rceil$ -bit words identifying the active user in each cell.

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